

LINEAR INDUCTION MOTOR



Electrical and Computer Engineering

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10/1/2015

Outline of Presentation

- Background Information
- Design Approach
- Economic Analysis
- Societal and Environmental Impacts
- Timeline
- Division of Labor
- Conclusion

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Background Information

Linear Induction Motor Background

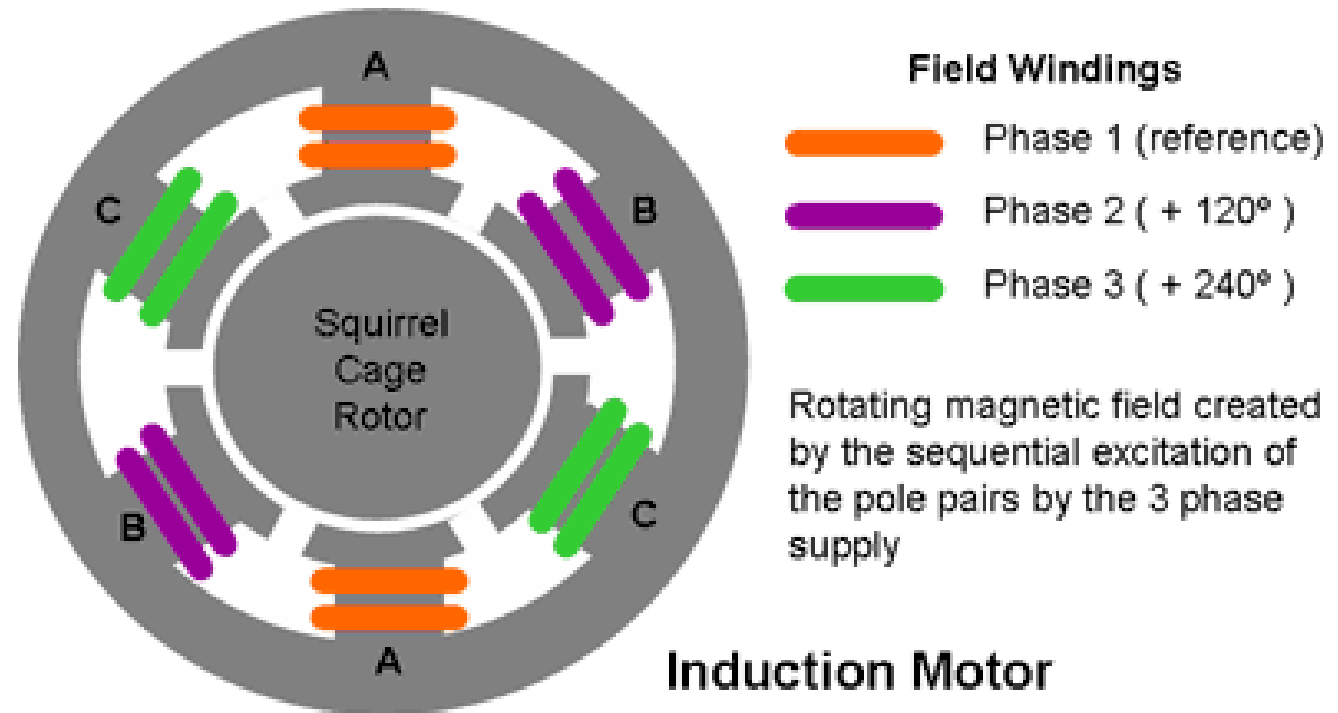
- Alternating Current electric motor
- Powered by a multiple phase voltage scheme
- Force and motion are produced by a linearly moving magnetic field
- Used to turn large diameter wheels



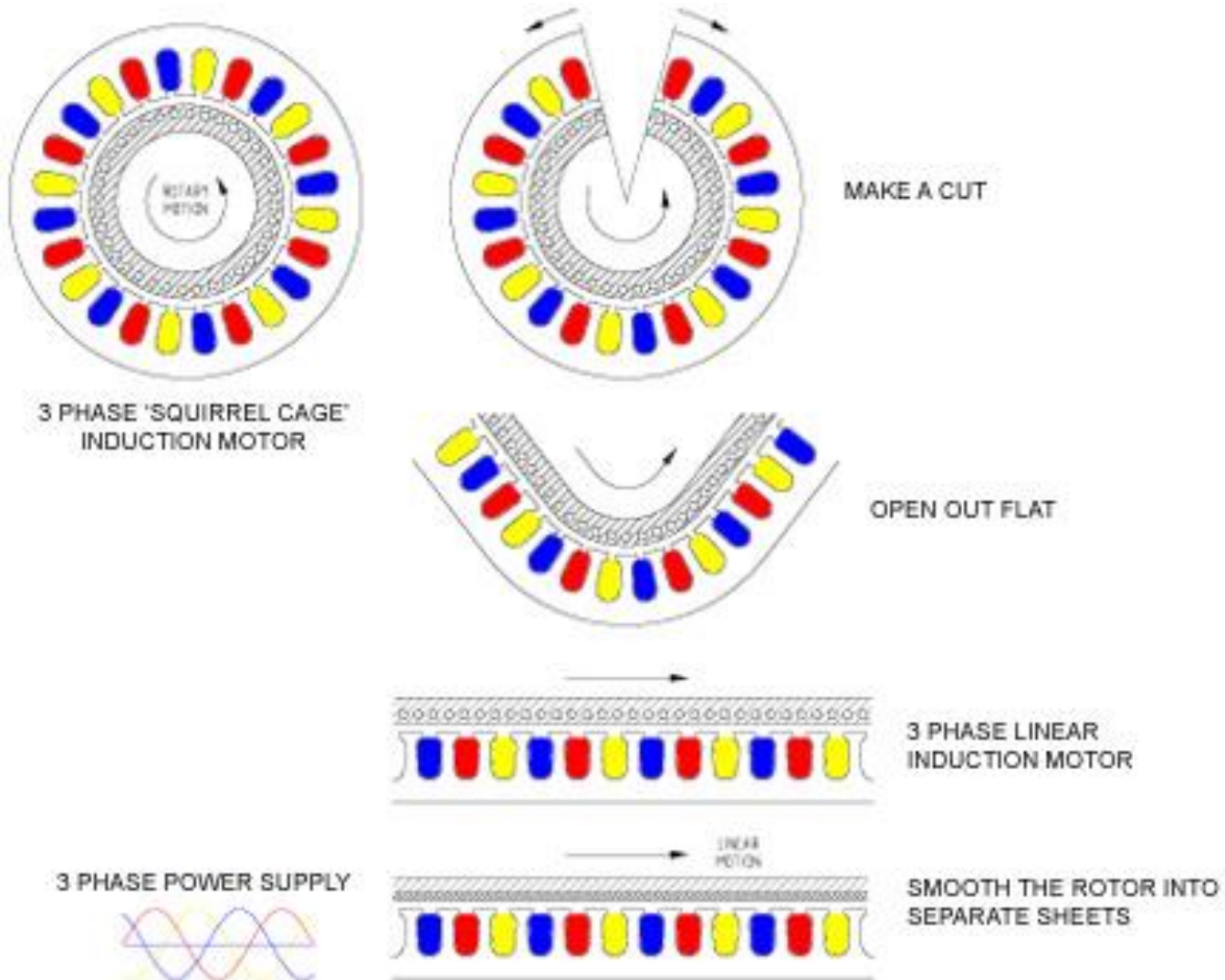
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Alternating Current Induction Machines

- Most common AC machine in industry
- Produces magnetic fields in an infinite loop of rotary motion
- Stator wrapped around rotor

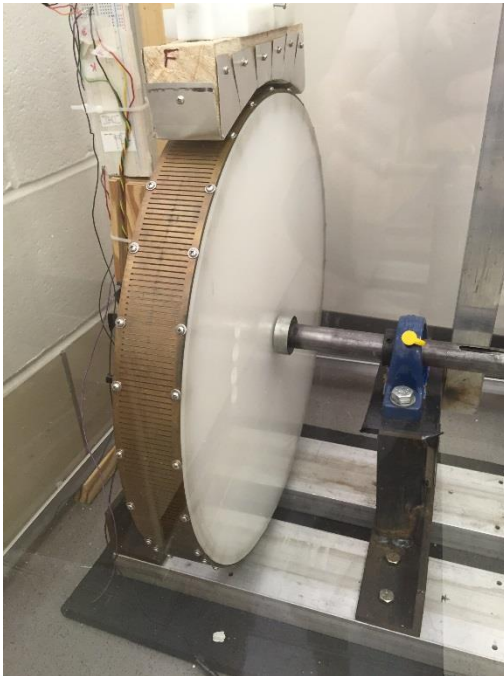


Rotary to Linear



Design Constraints

- 3 Phase Voltage Scheme
- Simulated linear track cannot exceed 1,100 rotations per minute (RPM)



[4]



[5]

Patent/ Product/ Literature Review

- Datasheets
 - Atmega 128 Documentation
 - Lenze Tech MH250B Documentation
- Journal
 - Design of a Single Sided Linear Induction Motor(SLIM) Using a User Interactive Computer Program [32]
- Books
 - Linear Induction Motor [33]
- Patents
 - Linear Induction Motor Construction [34]
 - Secondary member for single-sided linear induction motor [35]
 - Linear Induction Motor [36]

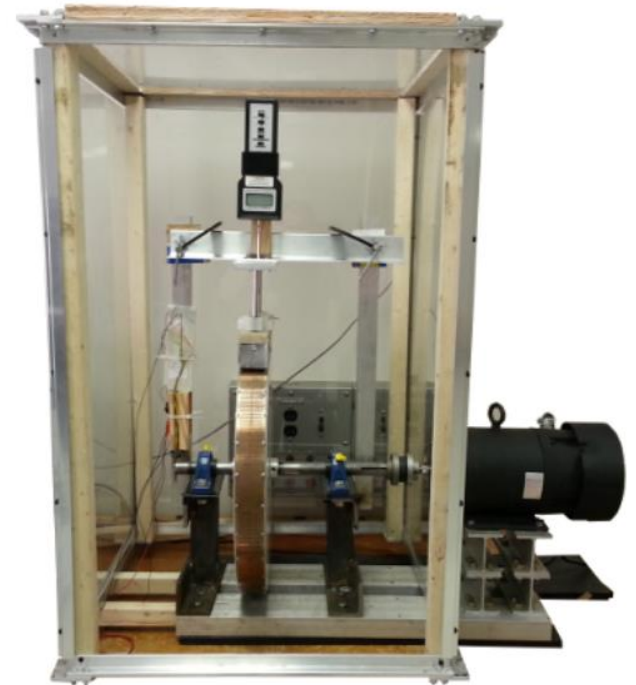
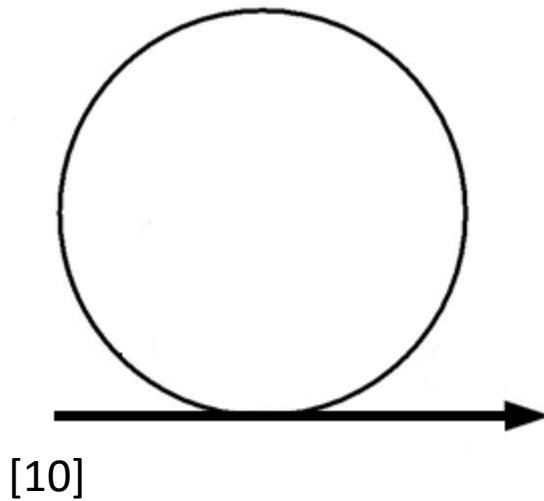
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Design Approach

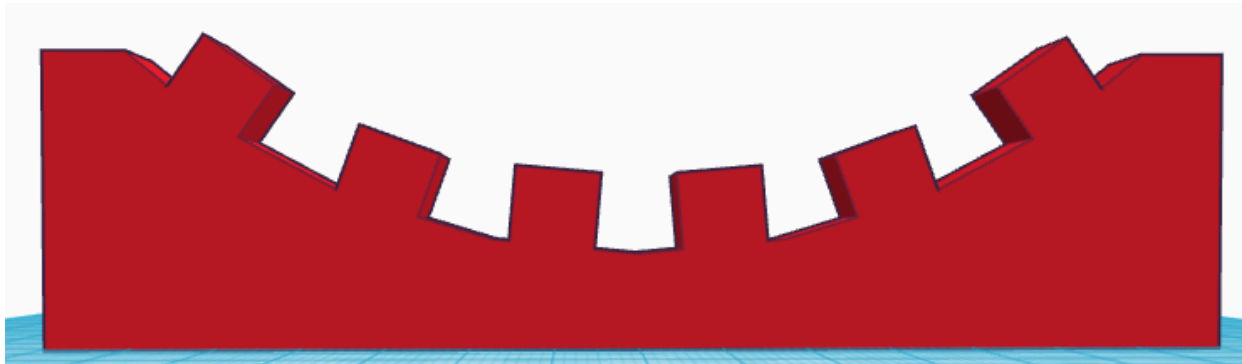
Problem

- Rotate the simulated linear track
- Rotate under safe speeds (<1100 RPM)



Solution to Problem

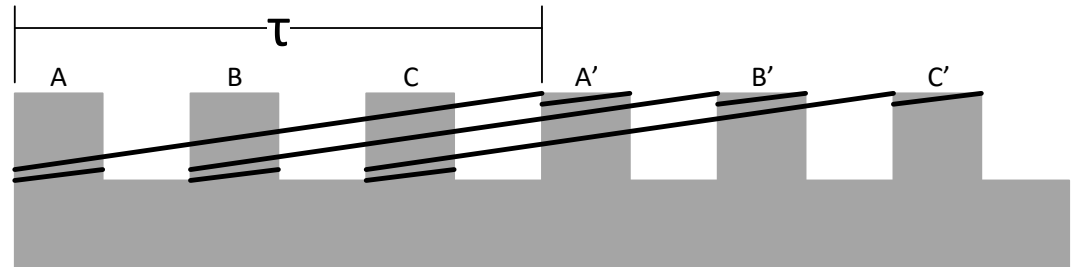
- Develop
- Design
- Implement a Linear Induction Motor to produce linear motion



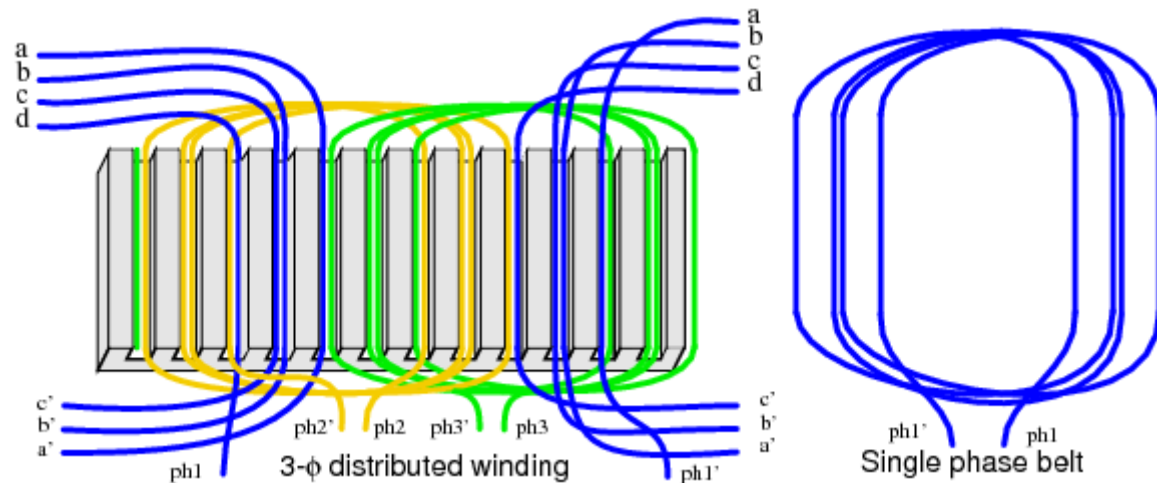
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Additional Research

- Pole Pitch
 - Design phase
- Pole Arrangements
 - Salient vs. non-salient
 - Design phase
- Interfacing sensors
 - Implementation phase



[13]



[14]

Key Components

- Stator Lamination Segments
- VFD
 - Lenze-tech MH250B
- Microcontroller
 - Atmega 128



[15]

Key Components Availability

- Stator
 - Design and have manufactured
- VFD
 - Provided by Caterpillar
- Microcontroller
 - Provided by Bradley



[16]



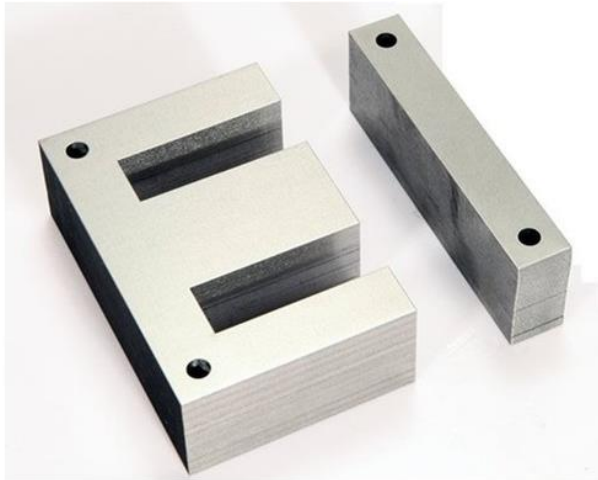
[17]

Alternative Solutions

- Lower velocity output
- Different material
- Change the number of poles
- Vary the dimensions of motor
- Lower frequency range

Alternative Components

- Solid manufactured stator
- Transformer E laminations
- Different Microcontroller



[18]



[19]

Skill Set Required

- Experience Interfacing components in C++
- MATLAB
- Understand of high level mathematics
- Power electronics
- Manufacturing skills

Multidisciplinary

- Main focus on Electrical Engineering
- Stator design may take some Mechanical Engineering background
 - May require additional help in 3-D modeling



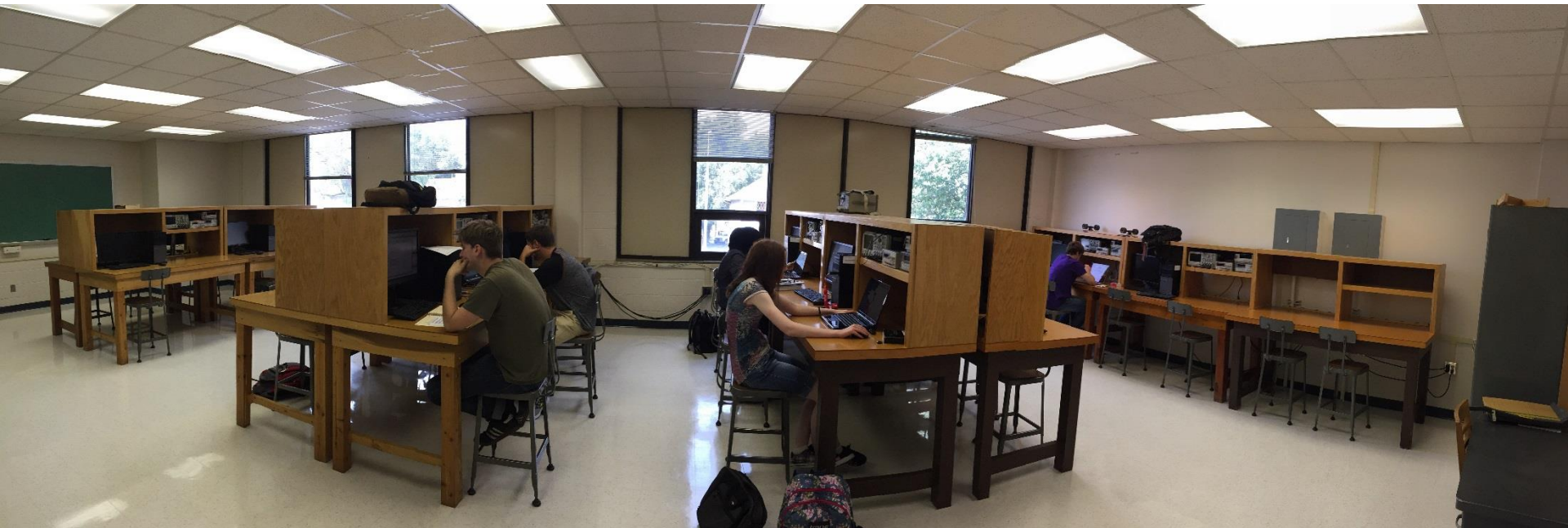
[20]



[21]

Work Locations

- Bradley University
 - Power Lab
 - Senior Lab



Experimentation

- Location – Power Lab
- Supervisor – Professor Gutschlag



Solution Testing

- Current measurements
- Efficiency calculations
- RPM measurements
- Torque measurements
- Comparison to simulated/calculated results

Criteria for Solution Testing

- Rotation of the simulated linear track
- Output max speed within 50% of calculated max speed

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Economic Analysis

Project Feasibility

- Highly feasible
- Work is divided equally
- Staying focused on objective goals

Consumer Market

- Lab Setting Only
- No Market
- Will not be sold

Overview of Total Component cost

Components	School Provided or Purchase	Cost (If Applicable)
Stator	Purchase	\$800.00
Variable Frequency Drive	School	\$848.00
Sensors	Purchase	\$20.00
Tachometer EE-SG3	School	\$2.00
Microcontroller/ LCD Screen	School	\$80.00
Miscellaneous	Purchase	\$100.00
	Total Cost:	\$1850.00

Cost Expenditures

Components	Cost
Stator	\$800.00
Sensors	\$20.00
Miscellaneous	\$100.00

Cost Constraints

- Major:
 - Stator
 - VFD
- Minor
 - Coil Windings
 - Tachometer photo-interrupter

Maintenance Cost

- Power consumption usage
- Dedicated Atmega128 Board for usage on only that device
- New coil windings



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Societal and Environmental Impacts

Affected Individuals

- The project group
 - Tyler Berchtold, Mason Biernat and Tim Zastawny
- Project Advisor
 - Professor Gutschlag
- Course Instructor
 - Doctor Sanchez
- Fellow students in ECE 498

Natural Resource

- Metal
 - Steel Laminates
 - Copper
- Reusing equipment instead of purchasing new equipment
 - VFD
 - Variac
 - Tachometer
 - ATmega128



Ethical Development

- Does not violate Human Rights
- Not a weapon of mass destruction
- Ethically Made
- Ethical Use



Ensuring Safety

- Respecting Power Lab rules
 - Always wear safety glasses
 - Work in pairs
 - Turn off power when not using
- Checking power connections to the motors
- Observing Motor for possible issues
- Monitoring sensors
- Construction and implementation is done correctly

Safety Concerns

- Putting unsafe current levels through the stator.
- Heat Levels on Stator
- RPM of Simulated Linear Track
- Unauthorized individual attempting to use
 - Children, Adults, Disabled



Outcomes of Ignoring Safety

- Stator meltdown
- Stator exploding
- Electrocution
- Fire
- Microcontroller and sensor destruction
- Simulated Linear Track vibrations
- Personal Injury



Additional Safety Protocol

- Used under proper supervision and settings
- More monitoring equipment
- Integrated heat sensor with sound alert when temperatures are too high
- Shielding around stator to prevent accidental contact
- Adequate airflow to allow for proper cooling

Liability Concerns

- Damage to lab space
- Injury to others



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Timeline / Division of Labor

High Level - Division of Labor

- Design
 - Microcontroller
 - Tyler
 - Stator
 - Mason and Tim
- Purchasing
 - Entire Group

High Level - Division of Labor

- Construction
 - Sensors
 - Tyler
 - Motor
 - Mason and Tim
- Implementation
 - Tyler, Mason and Tim
- Testing
 - Tyler, Mason and Tim

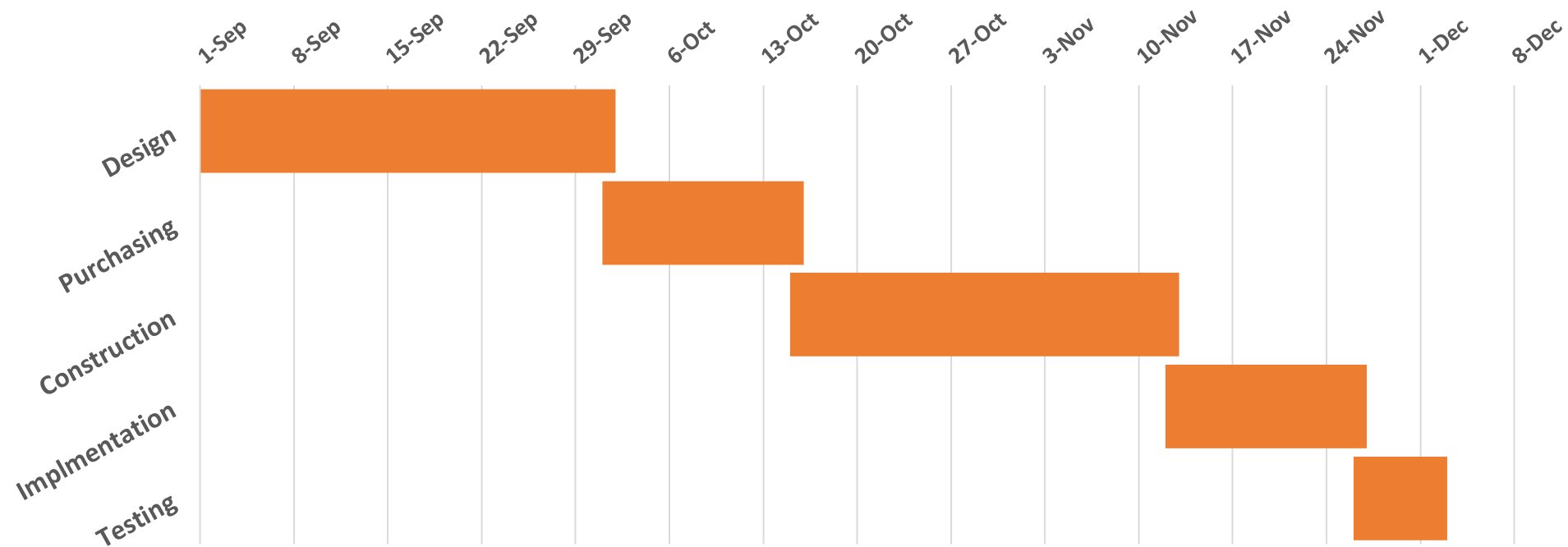
Interfacing Work – Tyler B.

- Interfacing
 - Input from Sensors
 - Tachometer
 - VFD Frequency
 - Voltage
 - LCD Screen
 - Voltage
 - Slip
 - Speed

Stator Work – Mason B. and Tim Z.

- Stator
 - Dimensions
 - Pole Pitch
 - Length
 - Width
 - Height
 - Mounting hardware
 - Coil Windings
 - Gauge
 - # of wraps

Gantt Chart – Main Components



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Conclusion

- Overall Goals:
 - Complete Design and Implementation of a linear machine
 - Prototype a linear stator
 - Develop working subsystems for control
 - Achieve linear motion
 - Gain experience
 - Power systems
 - Design and construction
 - Interfacing
 - Group dynamics
 - Useful engineering skills

Questions?

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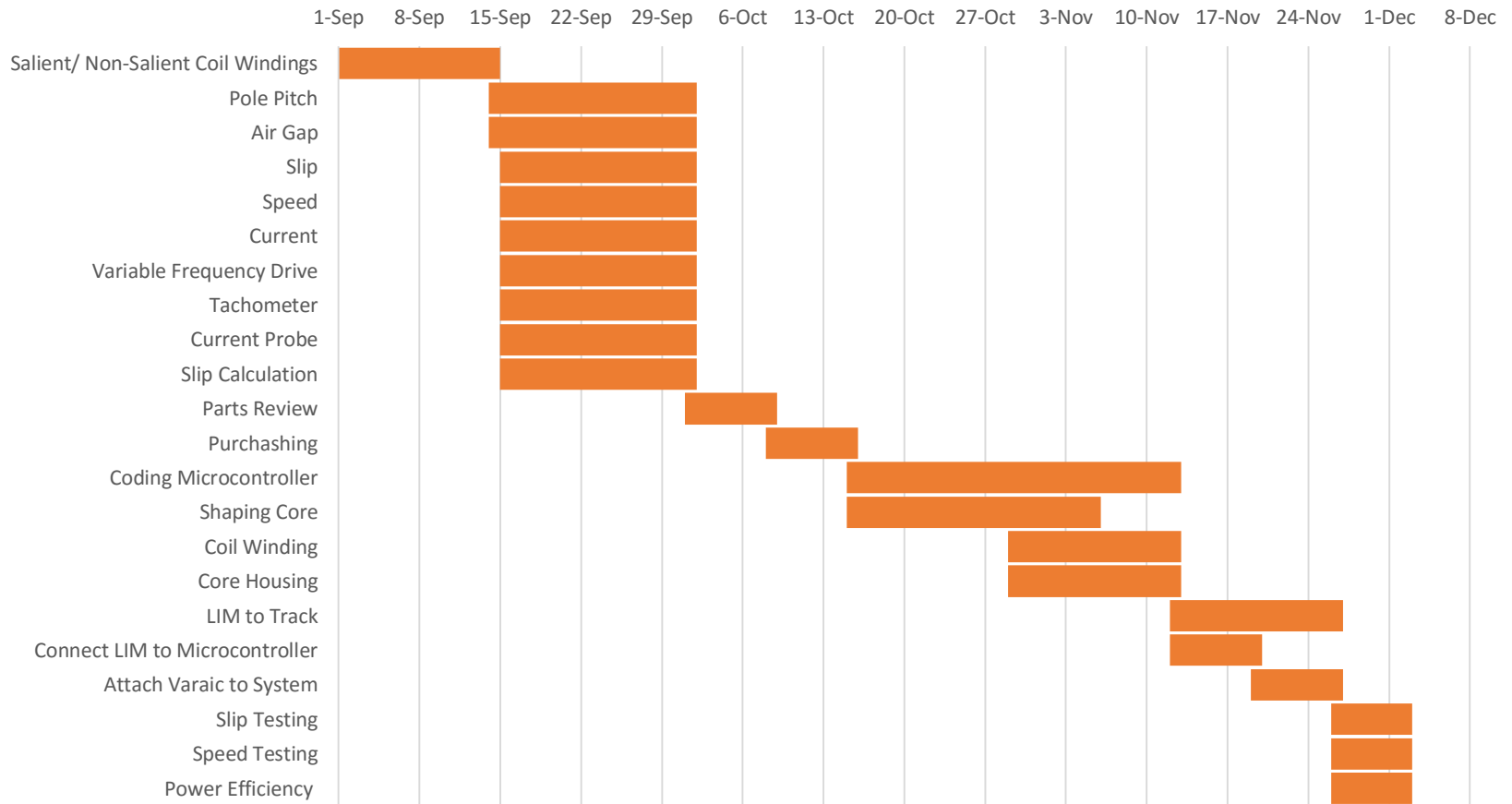
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Detailed Gantt Chart



Detailed Budget – Buying

Component	Cost
Stator Laminates	\$800.00
Copper Wire	\$10.00
Metal Bracing	\$50.00
Fasteners	\$10.00
Speed Sensor	\$5.00
Tachometer	\$2.00
Miscellaneous Small Components	\$100.00
Total Cost:	\$967.00

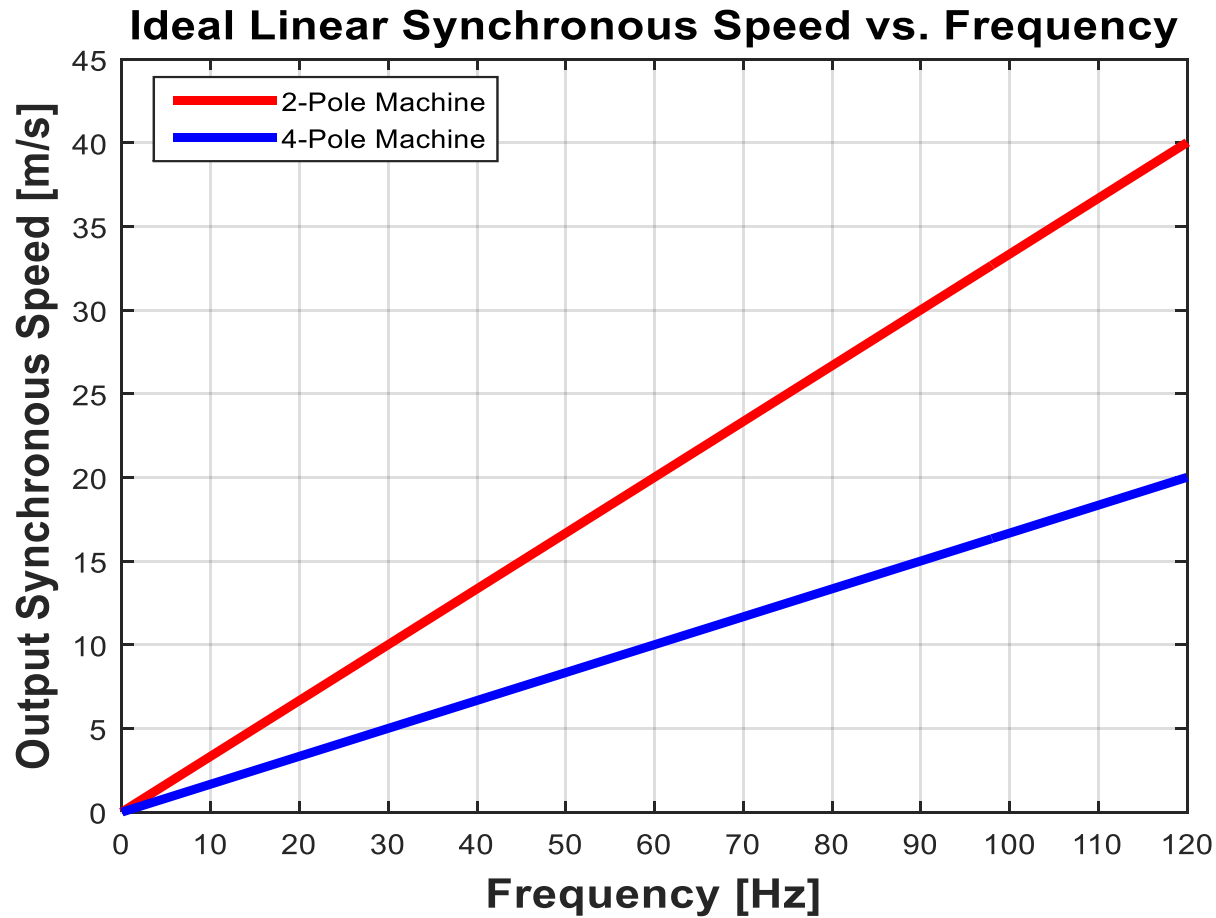
Equipment Already Have

Component
Simulated Linear Track
Variable Frequency Drive (Lenze AC Tech MH250B)
Variac
High Voltage Current Meter
Microcontroller (Atmega128)
Tachometer (EE-SG3)

Formal Test procedures

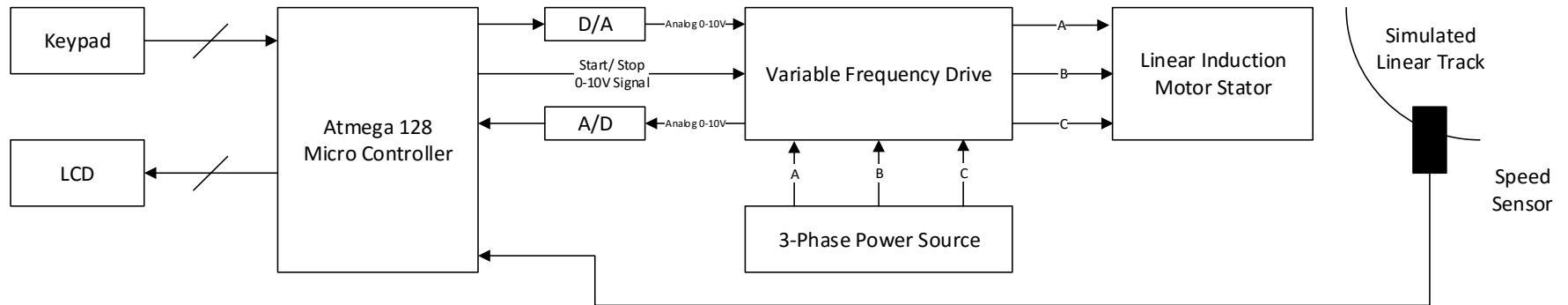
- Measuring input and output current
- Measuring torque
- Measuring speed
- Calculating efficiencies

Preliminary Test Results



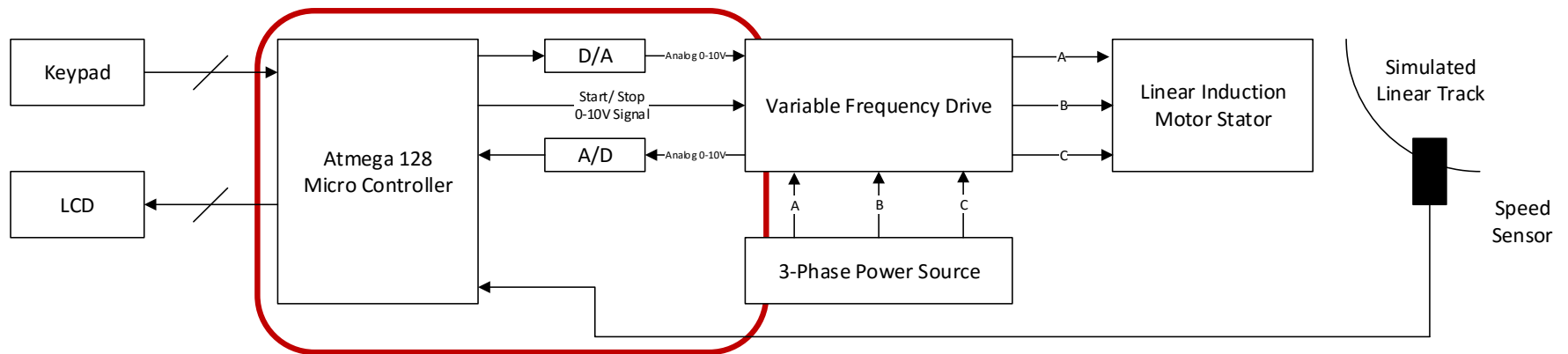
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Diagram of Entire System



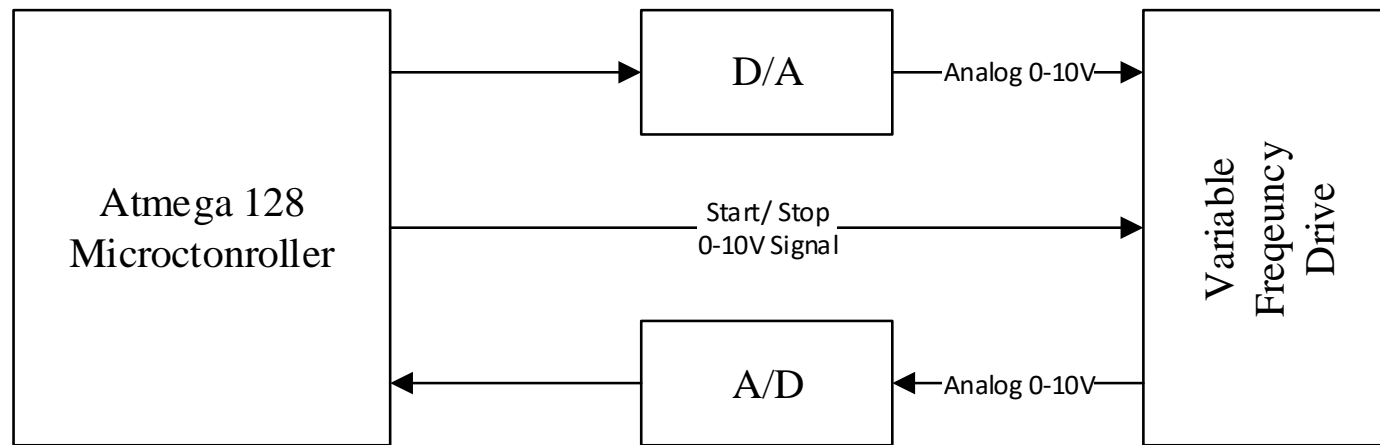
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Diagram of Entire System



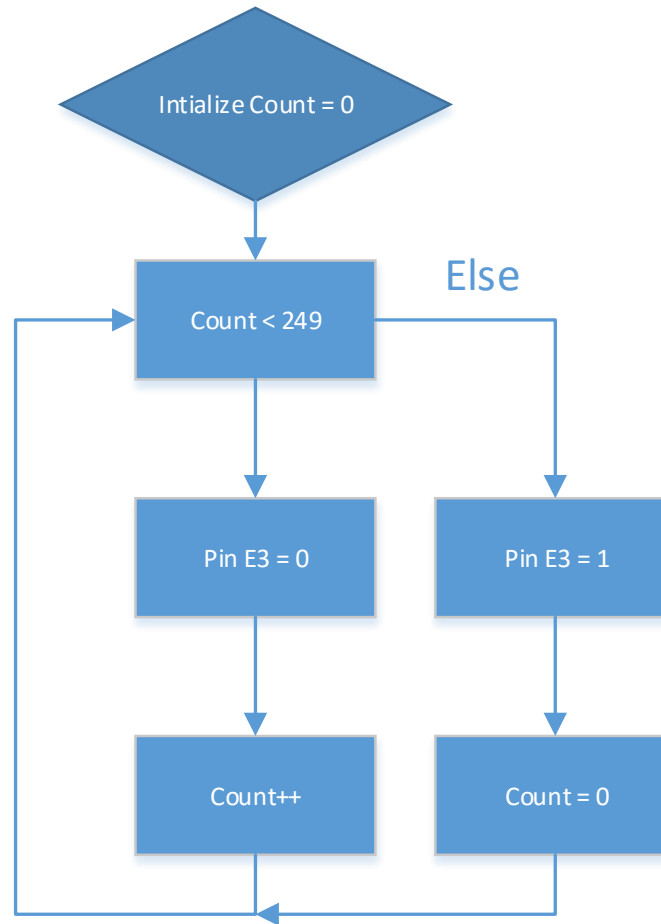
[29]

Close up of VFD System



[30]

Flowchart of Internal Interrupt



[31]